

Advanced Calculus

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Course web page https://www.math.uh.edu/~wagner/3334/math_3334_fall_2019.html

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The set of real numbers \mathbb{R} is a complete ordered field. It is the only one.

Properties:

- 1 Addition and multiplication are associative and commutative.
- 2 There is an additive identity, "1", and a multiplicative identity, "0".
- 3 Every real number x has an additive inverse, which is a real number $-x$, such that $x + (-x) = 0$.
- 4 Every non-zero real number x has a multiplicative inverse, which is a real number $\frac{1}{x}$, such that $x * (\frac{1}{x}) = 1$.

Properties 1 - 4 characterize \mathbb{R} as a field. Other fields include \mathbb{Q} , \mathbb{C} , \mathbb{Z}_p —the rational numbers, the complex numbers, and the integers mod p , when p is a prime number.

Order properties of \mathbb{R}

- 1 For every pair of real numbers x and y , exactly one of the following is true:

$$x = y, x > y, x < y.$$

- 2 If $x < y$ and $y < z$, then $x < z$, (Transitive)
- 3 If $x < y$, then $x + z < y + z$ for any $z \in \mathbb{R}$.
- 4 If $x < y$ and $z > 0$, then $xz < yz$.

Have we left something out?

There are two ordered fields, \mathbb{Q} and \mathbb{R} .

Let's try to prove this:

If $x < y$ and $z < 0$, then $xz > yz$.

Multiplication of an inequality by a negative number reverses the inequality.

Proof

- If $x < y$ and $z < 0$,
- Then $0 - z > 0$,
- Why?
- (If $z < 0$, then $0 = -z + z < -z + 0 = 0 - z$.)
- so that $(0 - z)x < (0 - z)y$,
- and so $-xz < -yz$.
- Now add $xz + yz$ to both sides to get:
- $-xz + xz + yz < -yz + xz + yz$, or
- $yz < xz$. □

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Completeness

We assume that \mathbb{R} has the *least upper bound property*. This means that any set S of real numbers which has an upper bound has a least upper bound y , which may or may not belong to S . It follows that any set T of real numbers which is bounded below has a greatest lower bound.

Completeness

Some definitions and properties:

- We say that a real number x is an upper bound for a subset S of \mathbb{R} , if $y \leq x$ for all $y \in S$.
- We say that a real number x is a lower bound for a subset S of \mathbb{R} , if $y \geq x$ for all $y \in S$.
- We say that a real number x is a least upper bound for a subset S of \mathbb{R} , if x is
 - an upper bound for S , and
 - a lower bound for the set of upper bounds for S .
- A real number x is a least upper bound for a subset S of \mathbb{R} , if and only if, for every $\epsilon > 0$, there is an upper bound y for S such that $x < y < x + \epsilon$. (Exercise!)

Counting

We say that a set S is

- *Countable* if S is not finite (infinite) and S can be put in 1-1 correspondence with the natural numbers \mathbb{N} .
- *Uncountable* if S is infinite and not countable.

The set of all rational numbers is countable. The set of real numbers is uncountable. To see why this matters, consider a function f on \mathbb{R} for which $f(x) > 0$ for all $x \in \mathbb{R}$. Then $\sum_{x \in \mathbb{R}} f(x) = \infty$. But many countable sums (series) converge absolutely to a finite value.

Our old friend \mathbb{R}^n

You probably last saw \mathbb{R}^n in linear algebra class. It is the first, and most important, example of a vector space that we encounter.

What we need to know from linear algebra:

- $(x_1, \dots, x_n) + (y_1, \dots, y_n) = (x_1 + y_1, \dots, x_n + y_n) =$ vector sum.
- $c(x_1, \dots, x_n) = (cx_1, \dots, cx_n) =$ scalar multiplication.
- $(x_1, \dots, x_n) \cdot (y_1, \dots, y_n) = x_1y_1 + \dots + x_ny_n =$ the dot product.
- If $X = (x_1, \dots, x_n)$, $\|X\| = \sqrt{X \cdot X} =$ the *norm* of X .
- $|X \cdot Y| \leq \|X\| \|Y\|$, the Cauchy-Schwartz inequality.

Triangle Inequality

A norm is supposed to satisfy the *Triangle Inequality*. Let's see if this norm does.

- $\|X + Y\|^2 = (X + Y) \cdot (X + Y) = X \cdot X + 2X \cdot Y + Y \cdot Y,$
- $= \|X\|^2 + 2X \cdot Y + \|Y\|^2,$
- $\leq \|X\|^2 + 2\|X\| \|Y\| + \|Y\|^2,$
- $= (\|X\| + \|Y\|)^2.$
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Angles

The Cauchy-Schwartz inequality also gives us $\left| \frac{X}{\|X\|} \cdot \frac{Y}{\|Y\|} \right| \leq 1$. We get equality if and only if X and Y are parallel. This suggests that we identify $\frac{X}{\|X\|} \cdot \frac{Y}{\|Y\|}$ with $\cos(\theta)$ where θ is the angle between X and Y .

The most important angle for linear algebra or multi-variable calculus is the right angle, $\frac{\pi}{2}$, which has a cosine of 0. So we say that vectors X and Y in \mathbb{R}^n are orthogonal (a fancy word for perpendicular) if $X \cdot Y = 0$.

Hyperplanes

You may recall from Calculus III, that a plane through (x_0, y_0, z_0) with normal vector $(A, B, C) \neq 0$ has equation

$$\begin{aligned}(A, B, C) \cdot (x - x_0, y - y_0, z - z_0) \\ &= A(x - x_0) + B(y - y_0) + C(z - z_0) \\ &= 0.\end{aligned}$$

This plane is a surface with dimension 2 in \mathbb{R}^3 . Since, at any point of the surface, the set of vectors that are normal (perpendicular) to the surface has dimension 1, we say that the surface has co-dimension 1.

More Hyperplanes

Similarly, in \mathbb{R}^n , the equation

$$\begin{aligned} &(A_1, \dots, A_n) \cdot (x_1 - x_{10}, \dots, x_n - x_{n0}) \\ &= A_1(x_1 - x_{10}) + \dots + A_n(x_n - x_{n0}) = 0. \end{aligned}$$

describes a flat subset of \mathbb{R}^n with dimension $n - 1$, co-dimension 1, through (x_{10}, \dots, x_{n0}) , and with normal vector (A_1, \dots, A_n) , which we assume is not 0. We call this set "hyperplane". If we use the word "plane" to describe a subset of \mathbb{R}^n with $n > 3$, we should mean a flat set with dimension 2.

To determine the dimension of a hyperplane, let $y_i = x_i - x_{i0}$, $i = 1, \dots, n$. Then we have

$$A_1 y_1 + \dots + A_n y_n = 0.$$

This is a linear homogeneous equation for which the matrix $(A_1 \dots A_n)$ has rank 1, so that the null space has dimension $n - 1$.

Lines

Recall from Calculus III that there are several ways to describe a line in \mathbb{R}^3 with equations:

- **Scalar Parametric Equations:** $x = x_0 + v_1 t$, $y = y_0 + v_2 t$,
 $z = z_0 + v_3 t$, $-\infty < t < \infty$.
- **Vector Parametric Equations:**
 $(x, y, z) = (x_0, y_0, z_0) + (v_1, v_2, v_3) t$, $-\infty < t < \infty$.
- **Symmetric Equations:** $\frac{x-x_0}{v_1} = \frac{y-y_0}{v_2} = \frac{z-z_0}{v_3}$, when no $v_i = 0$.

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or $\mathbf{x} = \mathbf{x}_0 + \mathbf{v}t$.
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Line segments

If p and q are distinct points in \mathbb{R}^n , we can use $q - p$ as a direction vector for the line through p and q : $\mathbf{x} = p + \lambda(q - p)$, $-\infty < \lambda < \infty$. Then $0 \leq \lambda \leq 1$ corresponds to the closed line segment from p to q , which we denote as $[p, q]$.

Convexity

We say that a subset S of \mathbb{R}^n is *convex*, if for every pair p, q of points in S , the closed line segment $[p, q]$ is contained in S . Convexity is one of the most important concepts in mathematical analysis.

Open ball

The *open ball* in \mathbb{R}^n with radius $r > 0$ and center $x_0 \in \mathbb{R}^n$ is

$$B(x_0, r) = \{x \in \mathbb{R}^n : \|x - x_0\| < r\}.$$

We show that $B(0, r)$ is convex. Suppose $p, q \in \mathbb{R}^n$ so that $\|p\|, \|q\| < r$. Then for $0 \leq \lambda \leq 1$,

$$\|(1 - \lambda)p + \lambda q\| \leq (1 - \lambda)\|p\| + \lambda\|q\| < (1 - \lambda)r + \lambda r = r.$$

Here we have used the Triangle Inequality and the homogeneity of the norm.

Thus every point of the line segment $[p, q]$ is an element of $B(0, r)$. So $B(0, r)$ is convex.